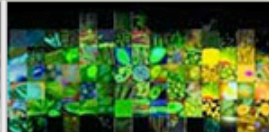




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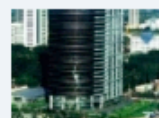
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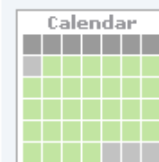
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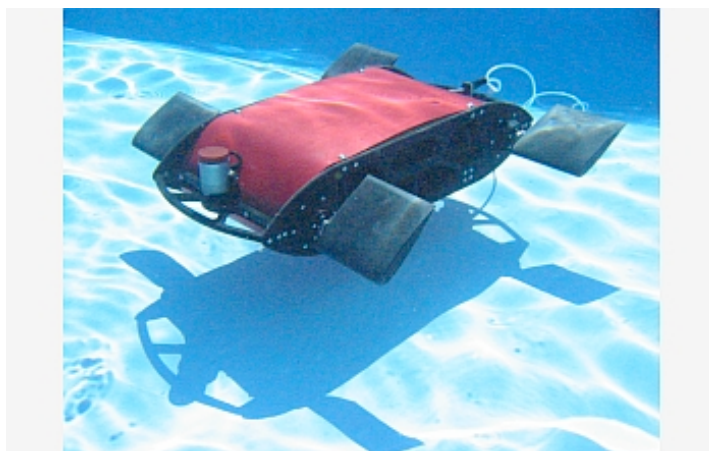
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Discovery

Swimming Robot Tests Theories About Locomotion in Existing and Extinct Animals

May explain why four-flipped swimmers now use only two



Madeleine is helping scientists and engineers better understand how flippers animals swim.

[Credit and Larger Version](#)

May 30, 2006

An underwater robot is helping scientists understand why four-flipped animals such as penguins, sea turtles and seals use only two of their limbs for propulsion, whereas their long-extinct ancestors seemed to have used all four.

When researchers put a joystick-controlled robot named Madeleine through her paces, they found that her top cruising speed did not increase when she used four flippers instead of two--apparently because the front flippers created turbulence that interfered with the rear flippers' ability to generate forward propulsion. Maintaining the same speed with four flippers also took significantly more energy. But Madeleine was able to make quicker starts and stops with all fours.

Results from experiments such as these aid engineers in designing underwater autonomous vehicles and help scientists understand why certain traits survived over others during the process of evolution.



Aquatic dinosaurs, called plesiosaurs, apparently used all four appendages for swimming.

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Researchers use the diving facility at Vassar College to test Madeleine's performance.

[Credit and Larger Version](#)



Madeleine's swim skin comes off after a dip.

[Credit and Larger Version](#)



Scientists who study fossils of four-limbed aquatic dinosaurs, such as plesiosaurs, say the shape and musculature of their appendages suggests they used all of their flippers for locomotion. But over time, the benefits of two-flippered swimming won out. Extrapolating from experiments with Madeleine, scientists hypothesize that plesiosaurs benefited from using all fours to ambush prey.

Bottles under Madeleine's swim skin house her computer, motor and batteries. [Credit and Larger Version](#)

Madeleine was developed by Vassar College's John Long and his colleagues at Nekton Research, LLC (Durham, N.C.) through support provided by the National Science Foundation's (NSF) Collaborative Research at Undergraduate Institutions program and the Major Research Instrumentation program.

Long was recently interviewed on "The Daily Planet," a program of Discovery Channel Canada. To watch the interview and see Madeleine in action, click [here](#).

--Randy Vines

Investigators

John Long

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Madeleine-related publications:

<http://faculty.vassar.edu/jolong/jolong.html>



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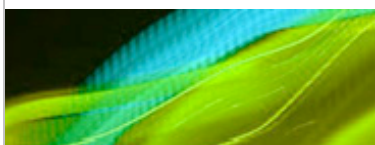
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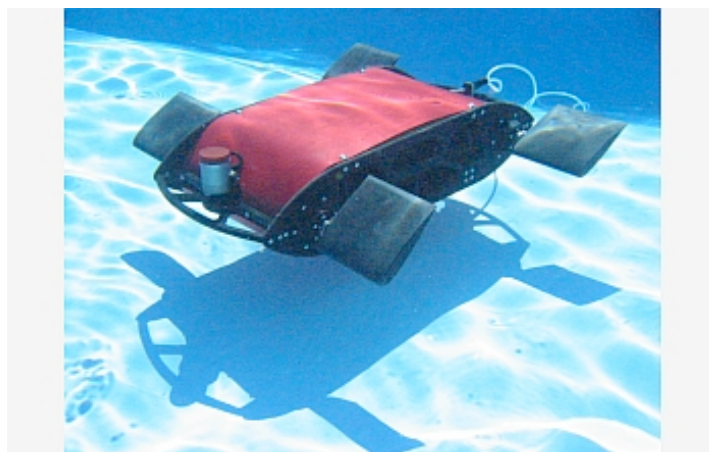
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Discovery

Swimming Robot Tests Theories About Locomotion in Existing and Extinct Animals

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Madeleine, a biologically inspired underwater robot, is helping scientists and engineers better understand the most energy-efficient way to use flippers for locomotion.

Credit: *John Long, Vassar College*

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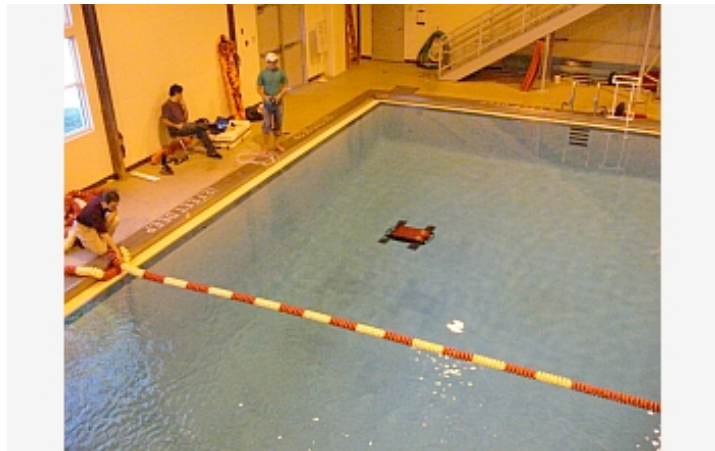


Scientists believe that unlike modern four-flipped animals, aquatic dinosaurs, called plesiosaurs, used all of their appendages for swimming. Madeleine is helping discover why the change to modern two-flipped swimming occurred. This plesiosaur representation was modeled after a skeletal fossil at the American Museum of Natural History in New York.

Credit: *Researched, modeled and composited by Frank DeNota.*

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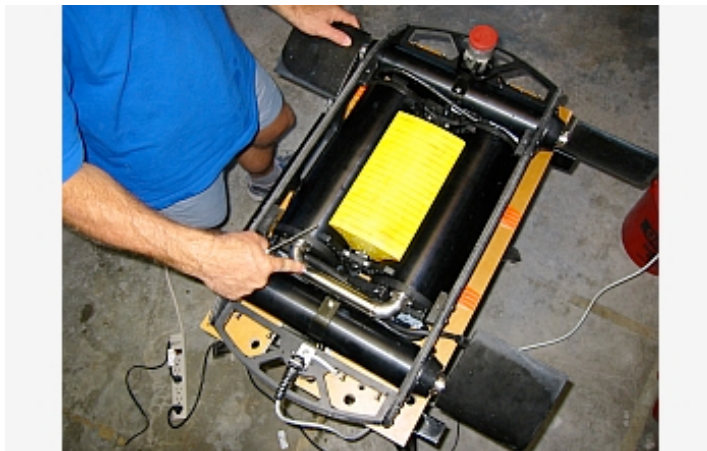


Undergraduate researchers use the diving facility at Vassar College to test Madeleine's performance.

Credit: *John Long, Vassar College*

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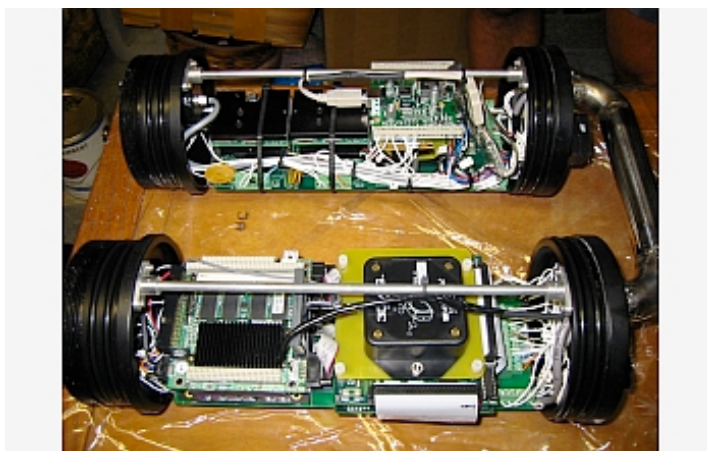


Madeleine's swim skin comes off after a dip. The oscillation of each flipper can be controlled independently to test the impact of different gaits on her motion.

Credit: *John Long, Vassar College*

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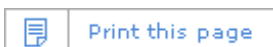


Waterproof black bottles under Madeleine's swim skin house her computer, motor and batteries.

Credit: *John Long, Vassar College*

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